

Solutions

MATH 314—Linear Algebra
Midterm 2
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- (1) Is \mathbb{R}^2 with the usual scalar multiplication $\alpha \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} \alpha x_1 \\ \alpha x_2 \end{pmatrix}$ and "addition" defined as $\begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \oplus \begin{pmatrix} y_1 \\ y_2 \end{pmatrix} = \begin{pmatrix} x_1 + y_1 \\ y_2 \end{pmatrix}$ a vector space? Justify your answer.

5 pts $\begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \oplus \begin{pmatrix} y_1 \\ y_2 \end{pmatrix} = \begin{pmatrix} x_1 + y_1 \\ y_2 \end{pmatrix} \neq \begin{pmatrix} y_1 + x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} y_1 \\ y_2 \end{pmatrix} + \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$
fails the commutative property
so \mathbb{R}^2 with the above scalar mult & addition is not a vector space

- (2) Determine if the following subsets are subspaces. In each case, justify your answer.

(a) $S = \{(x, x - y, x + y)^T \mid x, y \text{ real}\}$ in \mathbb{R}^3 ?

$$(x, x - y, x + y) + (z, z - w, z + w) = (x + z, x + z - y - w, x + z + y + w) \in S \quad (\text{so } + \text{ is closed})$$

5 pts $\alpha(x, x - y, x + y) = (\alpha x, \alpha x - \alpha y, \alpha x + \alpha y) \in S$
(so scalar mult closed)

Thus S is a subspace.

(b) $T = \{ax + 1 \mid a \text{ real}\}$ in P_1 ?

$$\alpha(ax + 1) = \alpha ax + \alpha \notin T$$

so scalar multiplication is not closed

5 pts so T is not a subspace.

(could have shown $+$ not closed or 0 not in T)

Note elements in T are of the form $ax + 1$ and $bx + 1$ (not $ay + 1$)

(3) Is $\left\{ \begin{pmatrix} 1 \\ 0 \\ 2 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 2 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ 4 \end{pmatrix}, \begin{pmatrix} 1 \\ 2 \\ 6 \end{pmatrix} \right\}$ a spanning set for \mathbb{R}^3 ?

$$\begin{pmatrix} 1 & 0 & 1 & 1 & | & x \\ 0 & 1 & 1 & 2 & | & y \\ 2 & 2 & 4 & 6 & | & z \end{pmatrix} \xrightarrow{R_3 - 2R_1} \begin{pmatrix} 1 & 0 & 1 & 1 & | & x \\ 0 & 1 & 1 & 2 & | & y \\ 0 & 2 & 2 & 4 & | & z - 2x \end{pmatrix}$$

$$\xrightarrow{R_3 - 2R_2} \begin{pmatrix} 1 & 0 & 1 & 1 & | & x \\ 0 & 1 & 1 & 2 & | & y \\ 0 & 0 & 0 & 0 & | & z - 2x - 2y \end{pmatrix}$$

10pts Since $z - 2x - 2y$ is not necessarily 0 there is no linear combination of the given 4 vectors for which we can obtain a random $\begin{pmatrix} x \\ y \\ z \end{pmatrix}$ so the vectors do not span \mathbb{R}^3 .

(4) Is $\left\{ \begin{pmatrix} 2 \\ 1 \\ 2 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \\ 1 \\ 4 \end{pmatrix} \right\}$ a linearly independent set in \mathbb{R}^4 ?

$$\begin{pmatrix} 2 & 0 & 1 \\ 1 & 1 & 0 \\ 2 & 1 & 1 \\ 0 & 1 & 4 \end{pmatrix} \xrightarrow{R_1 \leftrightarrow R_2} \begin{pmatrix} 1 & 1 & 0 \\ 2 & 0 & 1 \\ 2 & 1 & 1 \\ 0 & 1 & 4 \end{pmatrix} \xrightarrow{\begin{matrix} -2R_1 + R_2 \\ -2R_1 + R_3 \end{matrix}} \begin{pmatrix} 1 & 1 & 0 \\ 0 & -2 & 1 \\ 0 & -1 & 1 \\ 0 & 1 & 4 \end{pmatrix}$$

10pts

$$\xrightarrow{R_4 \leftrightarrow R_2} \begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 4 \\ 0 & -1 & 1 \\ 0 & -2 & 1 \end{pmatrix} \xrightarrow{\begin{matrix} R_2 + R_3 \\ 2R_2 + R_4 \end{matrix}} \begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 4 \\ 0 & 0 & 5 \\ 0 & 0 & 9 \end{pmatrix}$$

$$\xrightarrow{-1/5 R_3} \begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 4 \\ 0 & 0 & 1 \\ 0 & 0 & 9 \end{pmatrix} \xrightarrow{-9R_3 + R_4} \begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 4 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix}$$

Since there are no free variables and there are 3 pivots in row echelon form the vectors are linearly independent.

(5) Suppose V is a vector space of dimension 5. Answer the following questions.

(a) If v_1, v_2, v_3, v_4, v_5 are linearly independent vectors of V , do they span V ?

Yes since V is of dimension 5 and the vectors are linearly independent, they span.

(b) If v_1, v_2, v_3, v_4, v_5 are a spanning set for V , are they linearly independent in V ?

Yes since V is of dimension 5 and the vectors span they are linearly independent.

(c) Must a set of 6 vectors in V span V ?

No they may be linearly dependent and span a subspace of dimension 4 or less.

(d) Can a set of 4 vectors in V be linearly independent?

Yes since $4 < 5$, they could be linearly independent.

(6) Find the coefficient vector of $1 - 2x + 4x^3$ with respect to the basis $\{x^3, x^2, x, 1\}$ of P_3 .

$= B$

5 pts
$$\left[(1 - 2x + 4x^3) \right]_B = \begin{pmatrix} 4 \\ 0 \\ -2 \\ 1 \end{pmatrix}$$

(7) Determine if $L : P_2 \rightarrow P_3$ given by $L(p(x)) = xp(x) - x^2p'(x)$ is a linear transformation.

10 pts
$$\begin{aligned} L(p(x) + q(x)) &= x(p(x) + q(x)) - x^2(p(x) + q(x))' \\ &= xp(x) + xq(x) - x^2p'(x) - x^2q'(x) \\ &= xp(x) - x^2p'(x) + xq(x) - x^2q'(x) \\ &= L(p(x)) + L(q(x)) \end{aligned}$$

$$\begin{aligned} L(\alpha p(x)) &= x\alpha p(x) - x^2(\alpha p(x))' \\ &= \alpha xp(x) - \alpha x^2p'(x) \\ &= \alpha L(p(x)) \end{aligned}$$

so L is a linear transformation.

(8) Consider the bases $E = \left\{ \begin{pmatrix} 1 \\ 4 \end{pmatrix}, \begin{pmatrix} 2 \\ 7 \end{pmatrix} \right\}$ and $F = \left\{ \begin{pmatrix} 2 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \end{pmatrix} \right\}$ of \mathbb{R}^2 .

(a) Find the transition matrix from E to the standard basis.

5 pts $U = \begin{pmatrix} 1 & 2 \\ 4 & 7 \end{pmatrix}$ is the transition matrix from E to the standard basis.

(b) Find the transition matrix from the standard basis to F .

5 pts $V = \begin{pmatrix} 2 & 1 \\ 1 & 1 \end{pmatrix}$ is the transition matrix from F to the standard basis.

$V^{-1} = \frac{1}{2-1} \begin{pmatrix} 1 & -1 \\ -1 & 2 \end{pmatrix} = \begin{pmatrix} 1 & -1 \\ -1 & 2 \end{pmatrix}$ is the transition matrix from the standard basis to F .

(c) Find the transition matrix from E to F .

5 pts $V^{-1}U = \begin{pmatrix} 1 & -1 \\ -1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 2 \\ 4 & 7 \end{pmatrix} = \begin{pmatrix} -3 & -5 \\ 7 & 12 \end{pmatrix}$ is the transition matrix from E to F .

(d) Given $[\vec{v}]_E = \begin{pmatrix} -1 \\ 3 \end{pmatrix}$, what is $[\vec{v}]_F$?

5 pts $[\vec{v}]_F = \begin{pmatrix} -3 & -5 \\ 7 & 12 \end{pmatrix} \begin{pmatrix} -1 \\ 3 \end{pmatrix} = \begin{pmatrix} -12 \\ 29 \end{pmatrix}$

(9) Given the matrix $A = \begin{pmatrix} 3 & 3 & 2 & -1 & -4 \\ 1 & 1 & 1 & -1 & 2 \\ 1 & 1 & 0 & 0 & 1 \end{pmatrix}$, find:

$R_1 \leftrightarrow R_3$

(a) A basis for the row space of A.

$$\begin{pmatrix} 1 & 1 & 0 & 0 & 1 \\ 1 & 1 & 1 & -1 & 2 \\ 3 & 3 & 2 & -1 & -4 \end{pmatrix} \xrightarrow{\substack{-R_1+R_2 \\ -3R_1+R_3}} \begin{pmatrix} 1 & 1 & 0 & 0 & 1 \\ 0 & 0 & 1 & -1 & 1 \\ 0 & 0 & 2 & -1 & -7 \end{pmatrix}$$

+5

$$\xrightarrow{-2R_2+R_3} \begin{pmatrix} 1 & 1 & 0 & 0 & 1 \\ 0 & 0 & 1 & -1 & 1 \\ 0 & 0 & 0 & 1 & -9 \end{pmatrix} \text{ so } \left\{ \begin{pmatrix} 1 & 1 & 0 & 0 & 1 \end{pmatrix}, \begin{pmatrix} 0 & 0 & 1 & -1 & 1 \end{pmatrix}, \begin{pmatrix} 0 & 0 & 0 & 1 & -9 \end{pmatrix} \right\} \text{ are a basis of the row space of A.}$$

(b) A basis for the column space of A.

+3
 $R_3 + R_2$

Since there are pivots in the 1st 3rd and 4th columns then $\left\{ \begin{pmatrix} 3 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 2 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} -1 \\ -1 \\ 0 \end{pmatrix} \right\}$ are a basis of the column space.

(c) A basis for the nullspace of A.

+5

$$\begin{pmatrix} 1 & 1 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 & -8 \\ 0 & 0 & 0 & 1 & -9 \end{pmatrix} \begin{matrix} x_2 = s, x_5 = t \text{ are free} \\ \text{variables} \\ x_4 = 9t, x_3 = 8t \\ x_1 = -s - t \end{matrix}$$

so $\begin{pmatrix} -s-t \\ s \\ 8t \\ 9t \\ t \end{pmatrix} = s \begin{pmatrix} -1 \\ 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} + t \begin{pmatrix} -1 \\ 0 \\ 8 \\ 9 \\ 1 \end{pmatrix}$ and $\left\{ \begin{pmatrix} -1 \\ 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} -1 \\ 0 \\ 8 \\ 9 \\ 1 \end{pmatrix} \right\}$ are a basis of $N(A)$.

(d) What is the rank of A, the nullity of A? Exhibit that the rank-nullity theorem holds for this matrix.

$$\text{rank } A = 3 \quad \text{nullity } A = 2$$

+3

$3 + 2 = 5$ so rank nullity holds

(10) Find a matrix that represents the linear operator $L \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} x_3 \\ x_1 - x_2 \\ x_1 + x_2 \end{pmatrix}$ with

respect to the basis $E = \left\{ \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \right\}$.

$U = \begin{pmatrix} 0 & 0 & 1 \\ 1 & 1 & 0 \\ 1 & -1 & 0 \end{pmatrix}$ is the transition matrix from E to the standard basis

$A = \begin{pmatrix} L(\vec{e}_1) & L(\vec{e}_2) & L(\vec{e}_3) \end{pmatrix} = \begin{pmatrix} 0 & 0 & 1 \\ 1 & -1 & 0 \\ 1 & 1 & 0 \end{pmatrix}$ represents

L with respect to the standard basis

$$U^{-1} = \frac{1}{\begin{vmatrix} 0 & 0 & 1 \\ 1 & 1 & 0 \\ 1 & -1 & 0 \end{vmatrix}} \begin{pmatrix} 0 & 0 & -2 \\ -1 & -1 & 0 \\ -1 & 1 & 0 \end{pmatrix}^T = \frac{1}{-2} \begin{pmatrix} 0 & -1 & -1 \\ 0 & -1 & 1 \\ -2 & 0 & 0 \end{pmatrix}$$

$$= \begin{pmatrix} 0 & 1/2 & 1/2 \\ 0 & 1/2 & -1/2 \\ 1 & 0 & 0 \end{pmatrix}$$

The matrix representing L with respect to E is $U^{-1}AU = \begin{pmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 0 & 0 & 1 \\ 1 & 1 & 0 \\ 1 & -1 & 0 \end{pmatrix}$

$$= \begin{pmatrix} 0 & 0 & 1 \\ -1 & -1 & 0 \\ 1 & -1 & 0 \end{pmatrix}$$