

## Isometries

An isometry of  $\mathbf{R}^n$  is a map  $f : \mathbf{R}^n \rightarrow \mathbf{R}^n$  which *preserves* distances, that is

$$d(x, y) = d(f(x), f(y))$$

for any two points  $x, y \in \mathbf{R}^n$ . Unless otherwise stated, the distance function is the normal euclidean distance, that is

$$d((x_1, \dots, x_n), (y_1, \dots, y_n)) = \sqrt{(x_1 - y_1)^2 + \dots + (x_n - y_n)^2}.$$

An isometry is a very special type of symmetry.

1. Give some examples of isometries of  $\mathbf{R}^1$ ,  $\mathbf{R}^2$ ,  $\mathbf{R}^3$ . Do you think your list of examples is complete? How could you check?

2. Suppose  $f : \mathbf{R}^n \rightarrow \mathbf{R}^n$  is an isometry with the property that  $f(\vec{0}) = \vec{0}$ .
- Show that  $f$  is a *linear* map, that is that  $f(x + y) = f(x) + f(y)$  for any two vectors  $x, y$  and  $f(ax) = af(x)$  for any real number  $a$  and any vector  $x$  (Hint: show that  $f$  is determined by the images of the unit coordinate vectors— then conclude that  $f$  is linear).
  - What can you say about the matrix which represents  $f$  when  $f(\vec{0}) = \vec{0}$  (i.e. is it invertible, what is its determinant, . . .)?
  - How many degrees of freedom are there in choosing  $f$ ? The set of matrices representing these maps is called the *special orthogonal group* and is denoted  $SO(n)$ : here you have found the dimension of this space.

- 3.** Suppose we identify  $\mathbf{R}^n$  with the subset of  $\mathbf{R}^{n+1}$  consisting of vectors  $(x_1, \dots, x_n, 1)$  whose last coordinate is 1. Consider  $n + 1$  by  $n + 1$  matrices of the form

$$\begin{pmatrix} M & v \\ \vec{0} & 1 \end{pmatrix}$$

where  $M$  is an orthonormal  $n$  by  $n$  matrix,  $v$  is a (column) vector in  $\mathbf{R}^n$ , and  $\vec{0}$  denotes the zero (row) vector in  $\mathbf{R}^n$ .

- a.** Show that each of these matrices induces a symmetry of  $\mathbf{R}^n$ , with the given identification of  $\mathbf{R}^n$  with a subset of  $\mathbf{R}^{n+1}$ .
- b.** Show that the map in part **a** gives a one-to-one correspondence between symmetries of  $\mathbf{R}^n$  and a set of matrices.
- c.** Check that if  $M_1$  and  $M_2$  are any two matrices of this special form then  $M_1 M_2$  still has this form. Why does this *have* to be true, in light of part **b** of this problem?
- d.** For  $w \in \mathbf{R}^n$  let  $t_w : \mathbf{R}^n \rightarrow \mathbf{R}^n$  be translation by the vector  $w$ . Which matrix  $M$  represents this symmetry?

4. Consider the following distance function on  $\mathbf{R}^2$ :

$$\delta((x_1, x_2), (y_1, y_2)) = \max\{|x_1 - y_1|, |x_2 - y_2|\}.$$

- a. What are the isometries of  $\mathbf{R}^2$  with respect to  $\delta$ ?
- b. How does this compare to the isometries of  $\mathbf{R}^2$  relative to the euclidean distance function?

5. Another distance function on  $\mathbf{R}^2$  is the so-called discrete distance function

$$\delta'((x_1, x_2), (y_1, y_2)) = \begin{cases} 0 & \text{if } (x_1, x_2) = (y_1, y_2) \\ 1 & \text{if } (x_1, x_2) \neq (y_1, y_2) \end{cases}$$

- a. What are the isometries of  $\mathbf{R}^2$  with respect to  $\delta'$ ?
- b. How does this compare to the isometries of  $\mathbf{R}^2$  relative to the euclidean distance function?