

thm stronger criterion for instability

(1)

Assume $\vec{x}_0 = \vec{0}$, $\dot{\vec{x}} = \vec{f}(\vec{x})$, $\vec{f}(\vec{0}) = \vec{0}$.

$\vec{f} \in C^1(E)$, $E_{\text{open}} \subset \mathbb{R}^n$.

Define a function $U(\vec{x}) : E \rightarrow \mathbb{R}$, $E = \{ \vec{x} \in \mathbb{R}^n \mid |\vec{x}| \leq \kappa \}$

for $\kappa > 0$, $E \subset E_1$.

$U(\vec{x})$ has the following properties:

(1) $U(\vec{x}) \in C^1(E)$

(2) $U(\vec{0}) = 0$

(3) $\dot{U} > 0 \quad \forall \vec{x} \in E \setminus \vec{0}$, $\dot{U}(\vec{0}) = 0$

(4) $\forall \delta > 0 : \exists \vec{x} \in N_\delta(\vec{0})$ such that $U(\vec{x}) > 0$

$\Rightarrow \vec{0}$ is unstable.

Pf From (4):
that $\forall \delta$ s.t. $0 < \delta < \kappa$, $\exists \vec{x}_\delta$ such
 $0 < |\vec{x}_\delta| < \delta$ and $U(\vec{x}_\delta) > 0$.

Assume that $\vec{\Phi}_t(\vec{x}_\delta)$ is the flow.

Then we cannot have $\lim_{t \rightarrow \infty} \vec{\Phi}_t(\vec{x}_\delta) = \vec{0}$

because $U(\vec{0}) = 0 < U(\vec{x}_\delta)$ while $\dot{U}(\vec{x}) > 0$
for $\vec{x} \neq \vec{0}$ (from (3)).

Since $\dot{U} > 0$ for $\vec{x} \neq \vec{0}$ by (3) and U is
continuous by (1) and since $\vec{\Phi}_t(\vec{x}_\delta)$ is

bounded away from the origin (by continuity) ②

$\Rightarrow \exists m > 0 : \dot{u}(x_t(\vec{x}_\varepsilon)) \geq m > 0$ for $t \geq 0$
provided $|\Phi_t(\vec{x}_\varepsilon)| \leq K$.

But
$$u(\Phi_t(\vec{x}_\varepsilon)) - u(\vec{x}_\varepsilon) = \int_0^t \dot{u}(\Phi_s(\vec{x}_\varepsilon)) ds \geq mt \quad (*)$$

$\Rightarrow$ But $u(\vec{x})$ is continuous

$\Rightarrow$ it is bounded in E . But as $t \rightarrow \infty$

(*) implies that $\Phi_t(\vec{x}_\varepsilon)$ reaches

boundary: $\partial E = \{|\vec{x}| = K\}$.

$\Rightarrow \forall \varepsilon > 0, 0 < \varepsilon < K$, and $\forall \delta > 0$ but small,

$\exists \vec{\Phi}_0(\vec{x}_\varepsilon) : |\vec{\Phi}_0(\vec{x}_\varepsilon)| < \delta$ but $|\vec{\Phi}_t(\vec{x}_\varepsilon)| > \varepsilon$

for some $t \Rightarrow$ instability $\square$

(3)

$$\underline{\dot{x}} = \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix} \underline{x} + \begin{pmatrix} x_2^2 \\ x_1^2 \end{pmatrix}, \quad \underline{x} \in \mathbb{R}^2$$

$$U = x_2^2 - x_1^2 - \text{not sign definite}$$

$$\dot{U} = 2x_2 \dot{x}_2 - 2x_1 \dot{x}_1$$

$$= 2x_2 (x_2 + x_1^2) - 2x_1 (-x_1 + x_2^2)$$

$$= 2(x_1^2 + x_2^2) + 2x_1^2 x_2 - 2x_1 x_2^2$$

$$= 2(x_1^2 + x_2^2) + \underbrace{2x_1 x_2 (x_1 - x_2^2)}_{\downarrow \text{for } |\vec{x}| \rightarrow 0} > 0$$

$\Rightarrow 0$ is unstable by
above thm.