

Online Workshop on Stochastic Analysis

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Course outline:

Day 1 - Stochastic processes

Stochastic integrals

Semimartingales

Itô's lemma

Example SDEs, weak and strong solutions

Day 2 - Stochastic analysis in L^2

Solution of the stochastic heat equation

Day 3 - Vector-valued integration

Characterisation of UMD Banach spaces

Banach space valued stochastic analysis

Day 4 - von Neumann algebras and integration

Semi-commutative analysis

Calderón-Zygmund type decompositions

Motivating examples:

i. Consider a population growth model:

$$\frac{dP}{dt} = a(t)P(t)$$

We expect there to be random fluctuations over time. As such, let

$$a(t) = b(t) + \text{"noise"},$$

where $b(t)$ is deterministic.

This suggests two problems:

a. What kind of random process is the noise?

b. How can we integrate "against a random process"?

ii. Consider a financial market. Typically, "white noise", a continuous process models the random changes, however, unexpected events (such as a pandemic) may cause sudden large shifts in prices.

iii. An electrical circuit satisfies the equation

$$L \cdot Q''(t) + R \cdot Q'(t) + C^{-1} Q(t) = F(t),$$

for inductance L

resistance R

capacitance C

charge Q

potential source F

The potential source may suffer both from random noise, and power spikes / surges.

iv. Long term measurements may drift due to noise. (Allegedly, a nearby cum farm was a substantial source of interference for LEGO in Australia).

Consider tracking a satellite by measuring acceleration. The accumulation of errors will cause the measured position to drift. Can we "closely" approximate the true position?

I. Martingales and Stochastic Processes

Definition:

For a given probability space (Ω, Σ, μ) , and a linearly ordered index set T (e.g. $\mathbb{N}, \mathbb{R}_+, [0, k]$) a filtration on Ω is an increasing family of σ -algebras $(\Sigma_t)_{t \in T}$, ($s \leq t \Rightarrow \Sigma_s \subseteq \Sigma_t$).

We assume (Ω, μ) is complete. Furthermore, the filtration is said to satisfy the "usual hypotheses" if

- i. Σ_0 contains all μ -null sets of Σ
- ii. The filtration is right continuous,

$$\Sigma_t = \bigcap_{u > t} \Sigma_u.$$

We always assume the usual hypotheses.

For $t \in T$, let $E_t(X) = E(X | \Sigma_t)$ denote the conditional expectation onto Σ_t .

A stochastic process is a parameterised collection of random variables (μ -measurable functions) $\{X_t\}_{t \in T}$ over (Ω, μ) .

- While for fixed $t \in T$, $X_t(\omega)$ is a random variable over Ω , we may also fix $\omega \in \Omega$, and instead consider the path

$$t \mapsto X_t(\omega).$$

As such, we take $X_t(\omega)$ to be measurable in $T \times \Omega$.

- Identifying $\omega \in \Omega$ with the path

$$t \mapsto X_t(\omega) \in \mathbb{R}^T$$

induces a probability measure on $\hat{\Omega} = \mathbb{R}^T$ through the embedding

$$\Omega \leftrightarrow \hat{\Omega} = \mathbb{R}^T.$$

$$\omega \mapsto (X_t(\omega): T \rightarrow \mathbb{R})$$

Given stochastic processes $\{X_t\}_{t \in T}$, $\{Y_t\}_{t \in T}$, over Ω , say that:

- $\{X_t\}_{t \in T}$ is a modification of $\{Y_t\}_{t \in T}$ if for each $t \in T$,

$$\mu \{ \omega \in \Omega / X_t(\omega) = Y_t(\omega) \} = 1 \quad (X_t = Y_t \text{ a.s.})$$

- $\{X_t\}_{t \in T}$ is indistinguishable from $\{Y_t\}_{t \in T}$ if for almost all $t \in T$, $X_t = Y_t$.

A stochastic process $\{X_t\}_{t \in T}$ is said to be adapted to the filtration $(\Sigma_t)_{t \in T}$ if for each $t \in T$, X_t is Σ_t -measurable.

A martingale is an adapted real-valued stochastic process $\{X_t\}_{t \in T}$, such that for any $t \in T$,

i. $\mathbb{E}(|X_t|) < \infty$

ii. $\mathbb{E}_s(X_t) = X_s$, for all $s \leq t$.

If we replace condition (ii), $\{X_t\}_{t \in T}$ is a

ii'. $\mathbb{E}_s(X_t) \leq X_s$ - upper-martingale

ii''. $\mathbb{E}_s(X_t) \geq X_s$ - sub-martingale

Example:

i. Given a fair coin, let X_n denote the value of the n^{th} coin flip. $\{X_n\}_{n \in \mathbb{N}}$ is a martingale.

ii. Given $f \in L^2(\Omega, \Sigma, \mu)$, let $X_t = \mathbb{E}_t(f)$. Then $\{X_t\}_{t \in T}$ is a martingale, with limit f . Is the converse true?

Theorem: (Kolmogorov's Extension Theorem)

For all $t_1, \dots, t_k \in T$, $k \in \mathbb{N}$, if there exist probability measures ν_{t_1, \dots, t_k} on \mathbb{R}^{nk} , such that

i. for all permutations $\sigma \in \mathcal{S}_k$

$$\begin{aligned} \nu_{t_{\sigma(1)}, \dots, t_{\sigma(k)}} (F_1 \times \dots \times F_k) \\ = \nu_{t_1, \dots, t_k} (F_{\sigma^{-1}(1)} \times \dots \times F_{\sigma^{-1}(k)}) \end{aligned} \quad (K1)$$

ii. for all $m \in \mathbb{N}$

$$\nu_{t_1, \dots, t_k} (F_1 \times \dots \times F_k) = \nu_{t_1, \dots, t_k, t_{k+1}, \dots, t_m} (F_1 \times \dots \times F_k \times \mathbb{R}^{m-k})$$

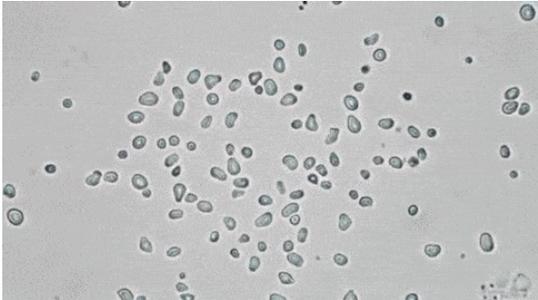
then there exists a probability space $(\Omega, \Sigma, \mathbb{P})$ and an \mathbb{R}^n -valued stochastic process $\{X_t\}_{t \in T}$ on \mathbb{R}^n , such

that

$$\nu_{k_1, \dots, k_2}(F_1 \times \dots \times F_k)$$

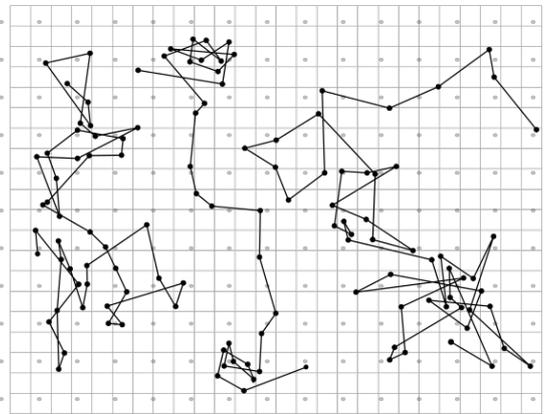
$$= \mathbb{P}(X_{k_1} \in F_1, \dots, X_{k_2} \in F_k)$$

for all $k_1, \dots, k_2 \in T$, $k \in \mathbb{N}$, Borel sets $F_1, \dots, F_k \subseteq \mathbb{R}^n$.



In 1828, Robert Brown noticed that pollen grains on the surface of water move irregularly. We can model this motion.

If we describe the behaviour of particles as measured satisfying (K_1, K_2) , we may then extend to a stochastic process.



i. For $x \in \mathbb{R}^n$, define

$$p(k; x, y) = \frac{1}{\sqrt{(2\pi k)^n}} \cdot \exp\left(-\frac{|x-y|^2}{2k}\right)$$

for all $y \in \mathbb{R}^n$, $k \in (0, \infty)$.

ii. For any $0 \leq k_1 \leq \dots \leq k_2$, define a measure

ν_{k_1, \dots, k_2} on $\mathbb{R}^{n \times k}$ by $\nu_{k_1, \dots, k_2}(F_1 \times \dots \times F_k) =$

$$\int_{F_1 \times \dots \times F_k} p(k_1; x, x_1) p(k_2 - k_1; x_1, x_2) \dots p(k_k - k_{k-1}; x_{k-1}, x_k) dx_1 \dots dx_k,$$

$F_1 \times \dots \times F_k$

with respect to the Lebesgue measure on \mathbb{R}^k , where

$p(0; x, y) dy = \delta_x(y)$,
for unit point mass δ .

Definition:

By Kolmogorov's extension theorem, there exists a stochastic process $\{B_t\}_{t \in (0, \infty)}$ on a probability space $(\Omega, \Sigma, \mathbb{P}^x)$, with joint distribution

$$\mathbb{P}^x(B_{t_1} \in F_1, \dots, B_{t_k} \in F_k) = \int_{F_1 \times \dots \times F_k} p(t_1; x_0, x_1) p(t_2 - t_1; x_1, x_2) \dots p(t_k - t_{k-1}; x_{k-1}, x_k) dx_1 \dots dx_k.$$

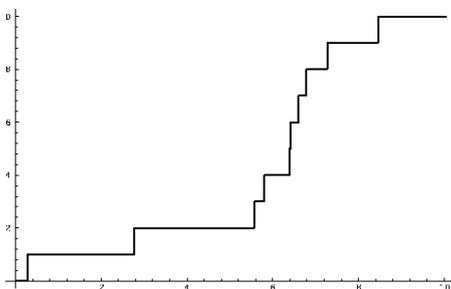
Call $\{B_t\}$ a Brownian motion starting at $x \in \mathbb{R}^n$.

Remark:

- The joint distribution \mathbb{P}^x does not uniquely define $\{B_t\}$.
- We may choose a modification of $\{B_t\}$ such that the sample paths $t \mapsto B_t(\omega)$ are continuous for almost all ω .
- It follows that Brownian motion is a probability measure \mathbb{P}^x on $C([0, \infty), \mathbb{R}^n)$. Call this the canonical Brownian motion.

Properties:

- $\{B_t\}$ is a Gaussian process, for any t_1, \dots, t_k , the joint distribution of B_{t_1}, \dots, B_{t_k} is a $n \times k$ dimensional multivariate normal distribution.
- $\{B_t\}$ has independent increments. For $0 \leq t_1 \leq \dots \leq t_k$, $B_{t_1}, B_{t_2} - B_{t_1}, \dots, B_{t_k} - B_{t_{k-1}}$ are independent random variables.



Let us now consider discontinuous processes. For example, a random number of customers arrive at a shop at random times.

Definition:

A stopping time is a random variable

$$\tau: \Omega \rightarrow [0, \infty],$$

such that $\{\omega \in \Omega: \tau(\omega) \leq t\} \in \Sigma_t$ for all t .

For stochastic process $\{X_t\}$, the stopped process

$\{X_{\tau \wedge t}\}$ is given by

$$X_{(\tau \wedge t)}(\omega), \text{ for all } \omega \in \Omega.$$

Let $(T_n)_{n \geq 0}$ be a strictly increasing sequence of positive random variables.

The process $(N_t)_{t \in T}: \Omega \rightarrow \mathbb{N} \cup \{\infty\}$, given by

$$N_t(\omega) = \sum_{n \geq 0} \chi_{\{t \geq T_n\}}(\omega),$$

where χ_E is the indicator function over the set Ω , is called a counting process.

Theorem:

A counting process is adapted if and only if the associated random variables $\{T_n\}_{n \geq 0}$ are stopping times.

An adapted counting process is said to be a Poisson process if

i. For any $0 \leq s < t$,

$N_t - N_s$ is independent of Σ_s ;

ii. For any $0 \leq s < t$, $0 \leq u < v$, $v - u = t - s$

implies that N_{v-u} has the same distribution as

$$N_{t-s}.$$

Theorem:

For any Poisson process $\{N_t\}$, and any $t \in T$, there exists $\lambda \geq 0$ such that

$$P(N_t = n) = \frac{e^{-\lambda t} (\lambda t)^n}{n!},$$

for $n \geq 0$. So, a Poisson process has Poisson distribution at time t , with parameter λt .

We are interested in processes which account for both continuous noise, and random jumps.

Definition:

An adapted process $(X_t)_{t \in T}$ is said to be a Lévy process if $X_0 \stackrel{a.e.}{=} 0$,

- i. $(X_t)_{t \in T}$ has increments independent of the past, in that for any $0 \leq s < t$, $X_t - X_s$ is independent of Σ_s ;
- ii. $(X_t)_{t \in T}$ has stationary increments; for $0 \leq s < t$, $X_t - X_s$ has the same distribution as X_{t-s} ;
- iii. $(X_t)_{t \in T}$ is continuous in probability;
 $\lim_{s \rightarrow t} X_s = X_t$ with probability 1.

A stochastic process is said to be càdlàg (or RCLL) if for almost every $\omega \in \Omega$, the path $t \mapsto X_t(\omega)$ is right continuous (RC) and all left limits exist (LL). This is an abbreviation of continue à droite, limites à gauche.

Theorem:

Every Lévy process admits a unique modification to a càdlàg Lévy process.

For a càdlàg process, time $t > 0$, let

$$X_{t-} = \lim_{s \rightarrow t^-} X_s,$$

and then let $\Delta X_t = X_t - X_{t-}$ denote any jump.

Theorem:

Let (X_t) be a Lévy process, with jumps bounded by a $(\sup_{s \geq 0} |\Delta X_s| \leq a \text{ a.s.})$, and set

$$Z_t = X_t - \mathbb{E}(X_t).$$

i. (Z_t) is a martingale.

$$\text{ii. } Z_t = Z_t^c + Z_t^d$$

iii. (Z_t^c) is a martingale with continuous paths.

iv. (Z_t^d) is a martingale defined by

$$Z_t^d = \left(\int_{|x| \leq a} x(N_t(\cdot, dx) - t\nu(dx)) \right)$$

for counting process (N_t) , "Lévy measure" ν .
(See Protter for details).

v. (Z_t^c) and (Z_t^d) are independent Lévy processes.

Theorem: (Lévy Decomposition Theorem)

Given Lévy process (X_t) , there exists a Brownian motion (B_t) , a poisson process (N_t) which is independent of (B_t) , and Lévy measure ν such that

$$X_t = B_t + \alpha t + \sum_{\alpha \leq s \leq t} \Delta X_s \chi_{\{|\Delta X_s| \geq 1\}}$$

$$+ \left(\int_{|x| < 1} x(N_t(\cdot, dx) - t\nu(dx)) \right)$$

II. Stochastic Integration and Differential Equations

Definition:

A stochastic process (H_t) is said to be a simple predictable process, if

$$H_t = H_0 \mathbb{1}_{\{0\}}(t) + \sum_{j=0}^n H_j \mathbb{1}_{(\tau_j, \tau_{j+1}]}(t),$$

for random variables $H_j \in L^0(\Omega, \Sigma_{\tau_j})$, and a finite collection of stopping times

$$0 = \tau_0 \leq \dots \leq \tau_{n+1} < \infty.$$

Let \mathcal{S} denote the collection of simple predictable processes. Let \mathcal{S}_u denote \mathcal{S} , taken with the topology of uniform convergence over $T \times \Omega$. Also, let \mathcal{L} denote the space of "finite random variables" (real valued measurable functions) over Ω , considered with the topology given by convergence in probability.

We would like stochastic integrals

- i. to be linear;
- ii. to satisfy the bounded convergence theorem.

For a given stochastic process X , define

$$I_X: \mathcal{S} \rightarrow \mathcal{L}^0$$

$$\text{by } I_X(H) = H_0 X_0 + \sum_{j=0}^n H_j (X_{\tau_{j+1}} - X_{\tau_j}).$$

Definition:

A stochastic process (X_t) is called a total semimartingale if X is càdlàg, adapted, and $I_X: \mathcal{S} \rightarrow \mathcal{L}^0$ is continuous.

A process $(X_t)_{t \in T}$ is called a semimartingale if for each $t \in T$, $(X_s)_{s \in (0, t)}$ is a total semimartingale.

Example:

- i. Any adapted process with càdlàg paths, and finite variation on compact intervals is a semimartingale.
- ii. Every L^2 -martingale with càdlàg paths is a semimartingale. (e.g. Brownian motion).
- iii. Definition:

An adapted process X , with càdlàg paths is said to be decomposable if

$$X_t = X_0 + M_t + A_t,$$

where $M_0 = A_0 = 0$, M is a locally square-integrable martingale, and A is càdlàg, adapted, and has paths of finite variation over compact sets.

Theorem:

Every decomposable process is a semimartingale.

Corollary:

Every Lévy process is a semimartingale.

Can we integrate processes which are not simple adapted?

Definition:

Let \mathcal{D} denote the space of adapted processes with càdlàg paths, and \mathcal{L} the space of adapted processes with càglàd (RLLC) paths. Then let $b\mathcal{L}$ be the subspace of processes in \mathcal{L} with bounded paths.

Definition:

A sequence $(H^n)_{n \geq 0}$ of stochastic processes converges to a process H uniformly on compact in probability (ucp) if for each $t > 0$,

$$\sup_{0 \leq s \leq t} |H_s^n - H_s|$$

converges to 0 in probability.

Denote

$$H_t^* = \sup_{0 \leq s \leq t} |H_s|.$$

Theorem:

The space \mathcal{S} is dense in \mathcal{L} under the ucp topology.

Definition:

Given $H \in \mathcal{S}$ and a càdlàg process X , define

$$\mathcal{I}_X: \mathcal{S} \rightarrow \mathcal{D}$$

by

$$\mathcal{I}_X(H) = H_0 X_0 + \sum_{j=0}^n H_j (X_{T_{j+1}} - X_{T_j}),$$

for stopping times $0 = T_0 \leq T_1 \leq \dots \leq T_{n+1} < \infty$.

We then call $\mathcal{I}_X(H)$ the stochastic integral of H with respect to X . $\mathcal{I}_X(H)$ may also be denoted by

$$\mathcal{I}_X(H) = \int H_s dX_s = H \cdot X.$$

Theorem:

For any semimartingale, the mapping

$$\mathcal{I}_X: \mathcal{S}_{ucp} \rightarrow \mathcal{D}_{ucp}$$

is continuous.

By density under the ucp topology, and since \mathcal{D}_{ucp} is a complete metric space, we may extend

$$\mathcal{I}_X: \mathcal{S} \rightarrow \mathcal{D}$$

to

$$\mathcal{I}_X: \mathcal{L} \rightarrow \mathcal{D}$$

by linearity.

Example:

What is $\int_0^t B_s dB_s$?

Let B denote a standard Brownian motion, with $B_0 = 0$.
Let $(\pi_n)_{n=1}^{\infty}$ be a refining sequence of partitions of $[0, \infty)$,
with $\lim_{n \rightarrow \infty} \text{mesh}(\pi_n) = 0$.

$$- B^n = \sum_{t_k \in \pi_n} B_{t_k} \chi_{(t_k, t_{k+1}]}$$

- $(B^n)_n$ converges to B in the ucp topology.

$$- \text{If } t \in \pi_n \text{ for all sufficiently large } n,$$
$$\int_B (B^n)_t = \sum_{\substack{t_k \in \pi_n \\ t_k < t}} B_{t_k} (B_{t_{k+1}} - B_{t_k})$$

- So:

$$\int_B (B)_t = \lim_{n \rightarrow \infty} \int_B (B^n)_t$$

$$= \lim_{n \rightarrow \infty} \sum_{\substack{t_k \in \pi_n \\ t_k < t}} B_{t_k} (B_{t_{k+1}} - B_{t_k})$$

$$= \lim_{n \rightarrow \infty} \sum_{\substack{t_k \in \pi_n \\ t_k < t}} \left\{ \frac{1}{2} (B_{t_{k+1}} + B_{t_k}) (B_{t_{k+1}} - B_{t_k}) \right.$$

$$\left. - \frac{1}{2} (B_{t_{k+1}} - B_{t_k}) (B_{t_{k+1}} - B_{t_k}) \right\}$$

$$= \frac{1}{2} B_t^2 - \frac{1}{2} \lim_{n \rightarrow \infty} \sum_{\substack{t_k \in \pi_n \\ t_k < t}} (B_{t_{k+1}} - B_{t_k})^2$$

$$= \frac{1}{2} B_t^2 - \frac{1}{2} t \quad [\text{By variance of Brownian motion}]$$

That is to say that

$$\int_0^t B_s dB_s = \frac{1}{2} (B_t^2 - t).$$

Notation

For a stochastic process (Y_t) , define (Y_-) by

$$(Y_-)_t = \lim_{u \rightarrow t^-} Y_u. \quad [(Y_-)_0 = 0]$$

Definition:

Let X and Y be semimartingales.

The quadratic variation process of X is

$$[X, X] = ([X, X]_t)_{t \in T},$$

defined by

$$[X, X] = X^2 - 2 \int X - dX.$$

The quadratic covariation (or the bracket process)

of X and Y is defined by

$$[X, Y] = XY - \int X - dY - \int Y - dX.$$

Corollary: (Integration by parts)

$$XY = \int X - dY + \int Y - dX + [X, Y].$$

Definition:

Given a semimartingale X , let $[X, X]^c$ denote the path-by-path continuous part of $[X, X]$, such that

$$[X, X]_t = [X, X]_t^c + \sum_{0 \leq s < t} (\Delta X_s)^2.$$

Theorem: (Change of Variables)

For a finite variation process X , with right-continuous paths, $f \in C^1$ such that f' is continuous, then $(f(X_t))_{t \in T}$ is again a finite variation process, and

$$f(V_t) - f(V_0)$$

$$= \int_{(0, t]} f'(V_{s-}) dV_s + \sum_{0 \leq s < t} \{ f(V_s) - f(V_{s-}) - f'(V_s) \Delta V_s \}.$$

Theorem: (Itô's Lemma)

Let X be a semimartingale, and f a real C^2 function. Then, $f(X)$ is a semimartingale, and

$$\begin{aligned}
 f(X_t) - f(X_0) &= \int_{(0,t]} f'(X_{s-}) dX_s + \frac{1}{2} \int_{(0,t]} f''(X_{s-}) d[X, X]_s^c \\
 &\quad + \sum_{0 < s < t} \left\{ f(X_s) - f(X_{s-}) - f'(X_{s-}) \Delta X_s \right\}.
 \end{aligned}$$

Corollary:

If X is a continuous semimartingale, and f is a real C^2 function, then $f(X)$ is a semimartingale and

$$f(X_t) - f(X_0) = \int_{(0,t]} f'(X_s) dX_s + \frac{1}{2} \int_{(0,t]} f''(X_s) d[X, X]_s.$$

Tomorrow we will discuss the solution of SDEs.

To conclude, let us better understand what a semimartingale is.

Definition:

A stochastic process X is said to be a local martingale if it is càdlàg, and there exists an increasing sequence $(\tau_n)_{n \geq 0}$ of stopping times, such that

$$\lim_{n \rightarrow \infty} \tau_n = \infty \text{ a.e.}$$

and

$$(X_{t \wedge \tau_n})_{t \geq 0}$$

is a uniformly integrable martingale for each n .

$$\left[\lim_{n \rightarrow \infty} \sup_{k \geq 0} \int_{\tau_k}^{\tau_{k+1}} |Y_n| dP = 0 \right]$$

Definition:

An adapted càdlàg process A is of finite variation if almost all paths $t \mapsto A_t(\omega)$ are of finite variation on compact-intervals.

Theorem: (Bichteler - Dellacherie)

Let X be an adapted càdlàg process. The following are equivalent:

- i. X is a semimartingale.
- ii. X is decomposable, in that there exists a locally square integrable local martingale M , and a process A of finite variation, such that $M_0 = 0 = A_0$, and

$$X_t = X_0 + M_t + A_t.$$