Dual Frame Surveys

- $\bullet \ a \cup ab \cup b = U$
- Independent samples are taken from the two sampling frames



- Used when one frame does not cover whole population of interest, dual frame surveys can provide better coverage and cost less
- May want several survey modes (internet, telephone, personal)

Examples:

- Telephone Surveys Tucker et al,.2005
- Frame A: Landlines
- Frame B: Cell Phones
- No Telephones





- One Frame is a Proper Subset of Another Rare Events (Asthma Patients)
 Frame A: General population health survey Frame B: Survey of patients of allergists
- Frame A and Frame B are the same
 Frame A: Current Population Survey (CPS)
 Frame B: Survey of Income and Program Participation (SIPP)

Point Estimators in Dual Frame Surveys

• $\hat{Y}_{ab}(\beta) = \beta \hat{Y}_{ab}^A + (1-\beta) \hat{Y}_{ab}^B$ • $\hat{Y} = \hat{Y}_a + \hat{Y}_{ab} + \hat{Y}_b$ = $\hat{Y}_a + \beta \hat{Y}_{ab}^A + (1-\beta) \hat{Y}_{ab}^B + \hat{Y}_b$



- Cross-sectional
- Hartley (1962) (Choose β to minimize variance)
- Fuller & Burmeister (1972) (Optimal)
- Bankier (1986)
- Kalton & Anderson (1986) (Single frame)
- Skinner (1991) (Maximum likelihood)

Problems from Hartley and Fuller & Burmeister Estimators

- \bullet Choose β to minimize the variance
- $\bullet~\beta$ depend on y's
- Different set of weights for each variable
- Inconsistencies among estimates

 Y_1 = the number of men who are unemployed

 Y_2 = the number of women who are unemployed

 Y_3 = the number of people who are unemployed

In a complex survey, it will often be the case that $Y_1 + Y_2 \neq Y_3$

Single Frame Estimators

Bankier, 1986, Kalton and Anderson 1986

$$\hat{Y}_{S} = \sum_{i \in S_{A}} w_{i}^{*} y_{i} + \sum_{i \in S_{B}} w_{i}^{*} y_{i}$$

$$w_{i}^{*} = \begin{cases} 1/\pi_{i}^{A} & i \in a \\ 1/\pi_{i}^{B} & i \in b \\ 1/(\pi_{i}^{A} + \pi_{i}^{B}) & i \in ab \end{cases}$$

- Consider that all observations had been sampled from a single frame with modified weights for the overlap domain observations
- Easy to calculate
- Need to know the inclusion probabilities for both frames. We may not know the frame A inclusion probabilities for sample units selected from frame B that fall in domain ab.
- Single frame estimates depend only on inclusion probabilities and not on variances within the two frames. The resulting estimates can be far from optimal.

Pseudo-Maximum Likelihood (PML) (Skinner & Rao 1996)

- Skinner & Rao (1996)
- Modify MLEs for SRS
- Adjust for complex sampling design
- Single set of weights for all the variables
- Perform similarly to Fuller & Burmeister estimator in many surveys

Common case, N_A and N_B known, but N_{ab} unknown

$$\hat{N}_{ab,H} = \frac{p n_{ab}^A N_A}{n_A} + \frac{q n_{ab}^B N_B}{n_B} \tag{1}$$

where p+q=1

$$Var(\hat{N}_{ab,H}) = p^2 \left(\frac{N_A}{n_A}\right)^2 Var(n_{ab}^A) + q^2 \left(\frac{N_B}{n_B}\right)^2 Var(n_{ab}^B)$$

• n^A_{ab} and n^B_{ab} are hypergeometric random variabels

$$n_{ab}^{A} \sim \frac{\left(\begin{array}{c} N_{ab} \\ x \end{array}\right) \left(\begin{array}{c} N_{a} \\ n_{A} - x \end{array}\right)}{\left(\begin{array}{c} N_{A} \\ n_{A} \end{array}\right)}$$

$$n_{ab}^{B} \sim \frac{\begin{pmatrix} N_{ab} \\ x \end{pmatrix} \begin{pmatrix} N_{b} \\ n_{B} - x \end{pmatrix}}{\begin{pmatrix} N_{B} \\ n_{B} \end{pmatrix}}$$
$$Var(n_{ab}^{A}) = n_{A} \frac{N_{ab}}{N_{A}} (1 - \frac{N_{ab}}{N_{A}}) \frac{N_{A} - n_{A}}{N_{A} - 1}$$
$$Var(n_{ab}^{B}) = n_{B} \frac{N_{ab}}{N_{B}} (1 - \frac{N_{ab}}{N_{B}}) \frac{N_{B} - n_{B}}{N_{B} - 1}$$

Minimize $Var(\hat{N}_{ab,H})$, we have $p_{OH} = \frac{n_A N_b g_B}{n_A N_b g_B + n_B N_a g_A}$

where

$$g_A = \frac{N_A - n_A}{N_A - 1}$$

(2)

and

$$g_B = \frac{N_B - n_B}{N_B - 1}$$

substituting (2) for p into (1). (1) then reduces to a quadratic in $\hat{N}_{ab}\text{,}$

$$[n_A g_B + n_B g_A] \hat{N}_{ab,s}^2$$

$$- [n_A N_B g_B + n_B N_A g_A$$

$$+ n_{ab}^A N_A g_B + n_{ab}^B N_B g_A] \hat{N}_{ab,s}$$

$$+ [n_{ab}^A g_B + n_{ab}^B g_A] N_A N_B = 0$$

$$\hat{Y}_{srs} = (N_A - \hat{N}_{ab,srs})\hat{u}_{a,srs}^A + \hat{N}_{ab,srs}\hat{u}_{ab,srs}$$
$$+ (N_B - \hat{N}_{ab,srs})\hat{u}_{b,srs}^B$$

$$\hat{u}_{a,srs} = \sum_{s_a} \frac{y_i}{n_a}, \hat{u}_{ab,srs}^A = \sum_{s_A,s_{ab}} \frac{y_i}{n_{ab}^A}$$
$$\hat{u}_{b,srs} = \sum_{s_b} \frac{y_i}{n_b}, \hat{u}_{ab,srs}^B = \sum_{s_B,s_{ab}} \frac{y_i}{n_{ab}^B}$$
$$\hat{u}_{ab,srs} = (n_{ab}^A \hat{u}_{ab,srs}^A + n_{ab}^B \hat{u}_{ab,srs}^B) / (n_{ab}^A + n_{ab}^B)$$

Adjusted to Complex Surveys

$$\hat{u}_{a,srs} \to \hat{u}_a = \frac{\hat{Y}_a}{\hat{N}_a}, \hat{u}^A_{ab,srs} \to \hat{u}^A_{ab} = \sum_{s_A,s_{ab}} \frac{\hat{Y}^A_{ab}}{\hat{N}^A_{ab}}$$

$$\hat{u}_{b,srs} \to \hat{u}_b = \frac{\hat{Y}_b}{\hat{N}_b}, \hat{u}^B_{ab,srs} \to \hat{u}^B_{ab} = \sum_{s_B,s_{ab}} \frac{\hat{Y}^B_{ab}}{\hat{N}^B_{ab}}$$

$$\hat{u}_{ab,srs} = (n_{ab}^{A} \hat{u}_{ab,srs}^{A} + n_{ab}^{B} \hat{u}_{ab,srs}^{B}) / (n_{ab}^{A} + n_{ab}^{B}) \rightarrow \\ \hat{u}_{ab} = [\frac{n_{A}}{N_{A}} \hat{N}_{ab}^{A} \hat{u}_{ab}^{A} + \frac{n_{B}}{N_{B}} \hat{N}_{ab}^{B} \hat{u}_{ab}^{B}] / [\frac{n_{A}}{N_{A}} \hat{N}_{ab}^{A} + \frac{n_{B}}{N_{B}} \hat{N}_{ab}^{B}]$$

Pseudo-Maximum Likelohood (PML)(Skinner and Rao (1996))

$$\hat{Y}_{PML} = (N_A - \hat{N}_{ab,PML})\hat{u}_a^A + \hat{N}_{ab,PML}\hat{u}_{ab} + (N_B - \hat{N}_{ab,PML})\hat{u}_b^B$$

 \hat{N}^{PML}_{ab} is the smaller of the roots of the quadratic equation

$$px^2 - qx + r = 0 \tag{3}$$

where

$$p = n_A + n_B,$$

$$q = n_A N_B + n_B N_A + n_A \hat{N}_{ab}^A + n_B \hat{N}_{ab}^B,$$

and

$$r = n_A \hat{N}_{ab}^A N_B + n_B \hat{N}_{ab}^B N_A.$$

Optimal Choice of n_A and n_B

$$\hat{\boldsymbol{\eta}} = (\hat{u}_{a}^{A}, \hat{u}_{ab}^{A}, \hat{N}_{ab}^{A}/N, \hat{u}_{b}^{B}, \hat{u}_{ab}^{B}, \hat{N}_{ab}^{B}/N)'$$
(4)

$$\boldsymbol{\eta} = (u_a, u_{ab}, N_{ab}/N, u_b, u_{ab}, N_{ab}/N)'.$$
 (5)

Under certain condition, $\hat{oldsymbol{\eta}}$ is consistent for $oldsymbol{\eta}$, and

$$\tilde{n}^{1/2}(\hat{\boldsymbol{\eta}} - \boldsymbol{\eta}) \xrightarrow{d} N(0, \boldsymbol{\Sigma}),$$
 (6)

where Σ is a block-diagonal matrix with blocks Σ_A and Σ_B , Σ_A is the asymptotic covariance matrix of $\tilde{n}^{1/2}\hat{\eta}_A = \tilde{n}^{1/2}(\hat{u}_a^A, \hat{u}_{ab}^A, \hat{N}_{ab}^A/N)'$ and Σ_B is the asymptotic covariance matrix of $\tilde{n}^{1/2}\hat{\eta}_B = \tilde{n}^{1/2}(\hat{u}_b^B, \hat{u}_{ab}^B, \hat{N}_{ab}^B/N)'$.

- \hat{Y}_{PML} depends on n_A and n_B only via the ratio n_A/n_B
- Choose n_A/n_B to minimize $avar(\hat{N}_{ab,PML})$
- By delta method, \hat{Y}_{PML} is asymptotically normal with mean Y and variance $(N^2/n)\sigma_{PML}^2$

•
$$\sigma_{PML}^2 = \nabla' \Sigma \nabla$$

 $\nabla = [N_a/N, \theta N_{ab}/N, \phi(u_{ab} - u_a - u_b),$
 $N_b/N, (1 - \theta) N_{ab}/N, (1 - \phi)(u_{ab} - u_a - u_b)],$
 $\phi = n_A N_b/(n_A N_b + n_B N_a)$
and $\theta = n_A N_B/(n_A N_B + n_B N_A)$

• Setting

$$\begin{split} & u_a = u_b = 0, u_{ab} = 1 \text{ in } \nabla \\ & \sigma_{Ai}^2 = \sigma_{Bi}^2 = 0, \sigma_{Aij} = \sigma_{Bij} = 0 (i, j = 1, 2) \text{ in } \Sigma \\ & \bullet avar(\hat{N}_{ab,PML}) = (N^2/n) [\phi^2 \sigma_{A3}^2 + (1 - \phi)^2 \sigma_{B3}^2] \\ & \bullet \text{ Minimized when } \phi = \sigma_{B3}^2 / (\sigma_{A3}^2 + \sigma_{B3}^2) \\ & \bullet \text{ Equivalently, } n_A / n_B = N_a \sigma_{B3}^2 / (N_b \sigma_{A3}^2) \end{split}$$

Gross Flow Estimation in Single Frame Survey

- Blumenthal (1968) Multinomial Sampling
- Chen-Fienberg (1974), Stasny (1986) Two stage model, reduced parametrizations of general interest
- Stasny and Fienberg (1984, 1985), Stasny (1983, 1986, 1987, 1988) Continuous time model
- Holt and Skinner (1989) Use survey weights to estimate transition probabilities
- Singh and Rao (1995) Classification error
- Most assume SRS, do not account for survey design

- Lu and Lohr (2010) Gross flow estimation in dual frame surveys
 —Accounts for survey design
 - —-Consider the overlap domain estimation
 - —-Model missing data through two-stage procedure