

Solutions #25

Math. 314, p. 289

G.1 (1(a,f,g,h,j), 2, 10, 13)

1. Find the eigenvalues/eigenspaces for

$$(a) \begin{vmatrix} 3-r & 2 \\ 4 & 1-r \end{vmatrix} = (r-3)(r-1)-8 = r^2-4r-5 = (r-5)(r+1)$$

$$r=5: \begin{pmatrix} -2 & 2 \\ 4 & -4 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = 0 \rightarrow \hat{e}_5 = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

$$r=-1: \begin{pmatrix} 4 & 2 \\ 4 & 2 \end{pmatrix} \rightarrow \begin{pmatrix} 2 & 1 \\ 0 & 0 \end{pmatrix} \Rightarrow \hat{e}_{-1} = \begin{pmatrix} 1 \\ -2 \end{pmatrix}$$

$$(f) \begin{vmatrix} -r & 1 & 0 \\ 0 & -r & 0 \\ 0 & 0 & -r \end{vmatrix} = -r^3 = 0 \Rightarrow r=0, \text{ triple}$$

$$\begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = 0 \Rightarrow \hat{e}_0 = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \text{ only vector}$$

$$(g) \begin{pmatrix} 1 & 1 & 1 \\ 0 & 2 & 1 \\ 0 & 0 & 1 \end{pmatrix}: r_1=1 \text{ double; } r=2, \text{ simple}$$

$$r=1: \begin{pmatrix} 0 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{pmatrix} \rightarrow \begin{pmatrix} 0 & 1 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}: \hat{e}_{1,1} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \text{ or } \hat{e}_{1,2} = \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix}$$

$$r=2: \begin{pmatrix} -1 & 1 & 1 \\ 0 & 0 & 1 \\ 0 & 0 & -1 \end{pmatrix} \rightarrow \begin{pmatrix} -1 & 1 & 1 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix} \Rightarrow \hat{e}_2 = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$$

$$(h) \det \begin{pmatrix} 1-r & 2 & 1 \\ 0 & 3-r & 1 \\ 0 & 5 & -1-r \end{pmatrix} = (1-r) [(3-r)(-1-r)-5] = (1-r)(r^2-2r-8) \quad r=1, 4, -2$$

$$r=-2: \begin{pmatrix} 3 & 2 & 1 \\ 0 & 5 & 1 \\ 0 & 5 & 1 \end{pmatrix} \rightarrow \begin{pmatrix} 3 & 2 & 1 \\ 0 & 5 & 1 \\ 0 & 0 & 0 \end{pmatrix}: \hat{e}_{-2} = \begin{pmatrix} -1 \\ -1 \\ 5 \end{pmatrix}$$

$$r=1: \begin{pmatrix} 0 & 2 & 1 \\ 0 & 2 & 1 \\ 0 & 5 & -2 \end{pmatrix} \rightarrow \begin{pmatrix} 0 & 2 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & -4.5 \end{pmatrix}, \hat{e}_1 = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$$

6.1.1 \rightarrow h (continued)

$$r=4, \begin{pmatrix} -3 & 2 & 1 \\ 0 & -1 & 1 \\ 0 & 5 & -5 \end{pmatrix} \rightarrow \begin{pmatrix} -3 & 2 & 1 \\ 0 & -1 & 1 \\ 0 & 0 & 0 \end{pmatrix}; \hat{e}_4 = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$$

$$(j) \begin{vmatrix} -2-r & 0 & 1 \\ 1 & -r & -1 \\ 0 & 1 & -1-r \end{vmatrix} = - (r+2) \begin{vmatrix} -r & -1 \\ 1 & -1-r \end{vmatrix} + 1 \cdot \begin{vmatrix} 1 & -r \\ 0 & 1 \end{vmatrix} \\ = - (r+2) [(r+1)r+1] + 1 = - (r^3 + 3r^2 + 3r + 1) = - (r+1)^3$$

$r=-1$, triple

$$\begin{pmatrix} -1 & 0 & 1 \\ 1 & 1 & -1 \\ 0 & 1 & 0 \end{pmatrix} \rightarrow \begin{pmatrix} -1 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 1 & 0 \end{pmatrix} \rightarrow \begin{pmatrix} -1 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix}; \hat{e}_{-1} = \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}; \text{ only one.}$$

6.1.2 Show that the eigenvalues of a triangular matrix are the diagonal elements of the matrix.

Recall that if $T = \begin{pmatrix} t_{11} & & \\ & \ddots & \\ 0 & & t_{nn} \end{pmatrix}$ is triangular, then

$$\det T = t_{11} t_{22} \dots t_{nn} = \prod_{k=1}^n t_{kk}, \text{ the product of the diagonals.}$$

$$\text{Then } \det(T - \lambda I) = \begin{vmatrix} t_{11}-\lambda & & \\ & \ddots & \\ 0 & & t_{nn}-\lambda \end{vmatrix} = \prod_{k=1}^n (t_{kk} - \lambda) = 0$$

$$\Rightarrow \lambda_k = t_{kk}; k=1, \dots, n$$

6.1.10 Show that the matrix $A = \begin{pmatrix} \cos \vartheta & -\sin \vartheta \\ \sin \vartheta & \cos \vartheta \end{pmatrix}$ will have complex evals. if $\vartheta \neq n\pi$.

$$\det(A - \lambda I) = \begin{vmatrix} \cos \vartheta - \lambda & -\sin \vartheta \\ \sin \vartheta & \cos \vartheta - \lambda \end{vmatrix} = (\cos \vartheta - \lambda)^2 + \sin^2 \vartheta = \\ = \cos^2 \vartheta + \sin^2 \vartheta - 2\lambda \cos \vartheta + \lambda^2 = 0$$

$$\Rightarrow \lambda^2 - 2\lambda \cos \vartheta + 1 = 0$$

$$\lambda = \cos \vartheta \pm \sqrt{\cos^2 \vartheta - 1} = \cos \vartheta \pm i \sin \vartheta = e^{\pm i \vartheta}$$

which is complex unless $\vartheta = 2n\pi$ ($\lambda = 1$) or

$\vartheta = (2n+1)\pi$ ($\lambda = -1$). The matrix A represents a rotation by angle ϑ , so it can only have real eigenvalues/vectors for $\vartheta = \pi + 2n\pi$ (evalue -1, reversal) or $\vartheta = 2n\pi$ (evalue 1, identity).

$(e^{i\vartheta})$ rotates complex numbers by angle ϑ in \mathbb{C} -plane

G.1.13 > Let A be a 2×2 matrix and let

$p(\lambda) = \lambda^2 + b\lambda + c$ be the characteristic polynomial of A .

Show that $b = -\text{tr}(A)$ and $c = \det(A)$

~~$$\begin{vmatrix} \lambda - a_{11} & -a_{12} \\ -a_{21} & \lambda - a_{22} \end{vmatrix} = 0$$~~

$$\begin{vmatrix} a_{11} - \lambda & a_{12} \\ a_{21} & a_{22} - \lambda \end{vmatrix} = 0$$

$$\Rightarrow (\lambda - a_{11})(\lambda - a_{22}) - a_{12}a_{21} = 0$$

$$\Rightarrow \lambda^2 - (a_{11} + a_{22})\lambda + (a_{11}a_{22} - a_{12}a_{21}) = 0$$

$$\boxed{\lambda^2 - (\text{Tr } A)\lambda + \det A = 0}$$

Solutions

Math. 314 (p. 323)

6.2 (1c, 2c)

6.2.1c

$$\left. \begin{array}{l} y_1' = y_1 - 2y_2 \\ y_2' = -2y_1 + 4y_2 \end{array} \right\} \frac{d}{dt} \mathbf{y} = \begin{pmatrix} 1 & -2 \\ -2 & 4 \end{pmatrix} \mathbf{y} = A\mathbf{y}$$

$$|A - \lambda I| = \begin{vmatrix} 1-\lambda & -2 \\ -2 & 4-\lambda \end{vmatrix} = 0 \Rightarrow \lambda^2 - 5\lambda = 0 \Rightarrow \lambda(\lambda - 5) = 0$$

$$\lambda_1 = 0: \begin{pmatrix} 1 & -2 \\ -2 & 4 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = 0 \Rightarrow x_1 - 2x_2 = 0: x_1 = 2, x_2 = 1: \mathbf{v}_1 = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$$

$$\lambda_2 = 5: \begin{pmatrix} -4 & -2 \\ -2 & -1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = 0 \Rightarrow -4x_1 - 2x_2 = 0: x_1 = 1, x_2 = -2: \mathbf{v}_2 = \begin{pmatrix} 1 \\ -2 \end{pmatrix}$$

$$\mathbf{y}(t) = c_1 \begin{pmatrix} 2 \\ 1 \end{pmatrix} + c_2 e^{5t} \begin{pmatrix} 1 \\ -2 \end{pmatrix}$$

6.2.2c

$$y_1' = 2y_1 - 6y_3$$

$$y_2' = y_1 - 3y_3$$

$$y_3' = y_2 - 2y_3$$

$$\mathbf{y}' = \begin{pmatrix} 2 & 0 & -6 \\ 1 & 0 & -3 \\ 0 & 1 & -2 \end{pmatrix} \mathbf{y} = A\mathbf{y}$$

$$|A - \lambda I| = \begin{vmatrix} 2-\lambda & 0 & -6 \\ 1 & -\lambda & -3 \\ 0 & 1 & -2-\lambda \end{vmatrix} = (2-\lambda) \begin{vmatrix} -\lambda & -3 \\ 1 & -2-\lambda \end{vmatrix} - 6 \begin{vmatrix} 1 & -1 \\ 0 & 1 \end{vmatrix}$$

$$= (2-\lambda) \lambda(2+\lambda) + 3(2-\lambda) - 6 = -\lambda^3 + \lambda = 0$$

$$\Rightarrow \lambda(1-\lambda^2) = 0: \lambda = 0, +1, -1$$

$$\lambda_1 = 0: \begin{pmatrix} 2 & 0 & -6 \\ 1 & 0 & -3 \\ 0 & 1 & -2 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = 0 \Rightarrow$$

$$\begin{cases} x_1 - 3x_3 = 0 \\ x_2 - 2x_3 = 0 \end{cases} \Rightarrow \begin{cases} x_1 = 3 \\ x_2 = 2 \\ x_3 = 1 \end{cases}$$

$$\mathbf{v}_1 = \begin{pmatrix} 3 \\ 2 \\ 1 \end{pmatrix}$$

$$\begin{cases} x_1 - 6x_3 = 0 \\ x_2 - 3x_3 = 0 \end{cases} \Rightarrow \begin{cases} x_1 = 6 \\ x_2 = 3 \\ x_3 = 1 \end{cases}$$

$$\mathbf{v}_2 = \begin{pmatrix} 6 \\ 3 \\ 1 \end{pmatrix}$$

$$\lambda_2 = 1: \begin{pmatrix} 1 & 0 & -6 \\ 1 & -1 & -3 \\ 0 & 1 & -3 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = 0 \Rightarrow$$

$$\begin{cases} x_1 - 6x_3 = 0 \\ x_2 - 3x_3 = 0 \end{cases} \Rightarrow \begin{cases} x_1 = 6 \\ x_2 = 3 \\ x_3 = 1 \end{cases}$$

$$\mathbf{v}_3 = \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix}$$

$$\lambda_3 = -1: \begin{pmatrix} 3 & 0 & -6 \\ 1 & 1 & -3 \\ 0 & 1 & -1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = 0 \Rightarrow$$

$$\begin{cases} 3x_1 - 6x_3 = 0 \\ x_2 - x_3 = 0 \end{cases} \Rightarrow \begin{cases} x_1 = 2 \\ x_2 = 1 \\ x_3 = 1 \end{cases}$$

$$\mathbf{y} = c_1 \begin{pmatrix} 3 \\ 2 \\ 1 \end{pmatrix} + c_2 e^t \begin{pmatrix} 6 \\ 3 \\ 1 \end{pmatrix} + c_3 e^{-t} \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix}$$

$$\mathbf{y}(0) = \begin{pmatrix} 3 & 6 & 2 \\ 2 & 3 & 1 \\ 1 & 1 & 1 \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \\ c_3 \end{pmatrix} = \begin{pmatrix} 2 \\ 2 \\ 2 \end{pmatrix} \rightarrow \begin{pmatrix} 3 & 6 & 2 & | & 2 \\ 2 & 3 & 1 & | & 2 \\ 1 & 1 & 1 & | & 2 \end{pmatrix} \xrightarrow{-2} \begin{pmatrix} 1 & 1 & 1 & | & 2 \\ 2 & 3 & 1 & | & 2 \\ 3 & 6 & 2 & | & 2 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 1 & 1 & | & 2 \\ 0 & 1 & -1 & | & -2 \\ 0 & 3 & -1 & | & -4 \end{pmatrix}$$

$$\xrightarrow{\text{use third row}} \begin{pmatrix} 1 & 1 & 1 & | & 2 \\ 0 & 1 & -1 & | & -2 \\ 0 & 0 & 2 & | & 2 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 1 & 1 & | & 2 \\ 0 & 1 & -1 & | & -2 \\ 0 & 0 & 1 & | & 1 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 0 & 0 & | & 2 \\ 0 & 1 & 0 & | & -1 \\ 0 & 0 & 1 & | & 1 \end{pmatrix}$$

$$\Rightarrow c_1 = 2, c_2 = -1, c_3 = 1: \mathbf{y}(t) = 2 \begin{pmatrix} 3 \\ 2 \\ 1 \end{pmatrix} - \begin{pmatrix} 6 \\ 3 \\ 1 \end{pmatrix} e^t + \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix} e^{-t}$$